# OMRON

# **Mobile Robots**

# **LD** Series

# Autonomous Mobile Robots (AMRs)

Omron mobile robots are fully autonomous intelligent vehicles that increase throughput, reduce machine dwell time, eliminate errors, improve material traceability, and allow employees to focus on tasks that require complex human skills. What's more, unlike traditional AGVs, our mobile robots navigate by the natural features of the facility and require no expensive facility modification

LD Series mobile robots are easy to get up and running, requiring no construction such as the installation of magnets, and minimal programming. In addition, our software integrates with your other systems so you can get the solution up and running in minimal time.

- Easy to setup and operate
- Works safely with people
- Autonomous navigation doesn't require preset routes, magnets, beacons or facility modifications
- Easy to integrate with MES, ERP, and WMS systems
- Able to operate in fleets of up to 100 robots

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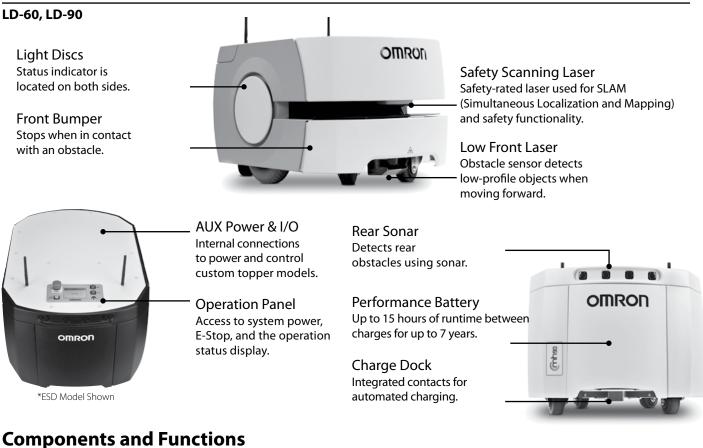
# Part Number Configuration

		1 Robot Type	Symbol
LD 60/ LD 90			0
Cart Transporter	·		1
LD 250			2
	2	Speed & Payload	Symbol
0.9m/s (Excludes LD 250)	90Kg (LD90)		6
0.911/S (EXCludes LD 250)	130Kg (Cart transport	ter)	0
1.2m/s (LD 250 Only)	250Kg		2
1.2m/s (Excludes LD 250)	90Kg (LD90)		4
I.3m/s (Excludes LD 250) 105Kg (Cart transporter)		4	
1.8 m/s/ (LD 60 Only)	) 60Kg		3
	[	3 Configuration	Symbol
Protection	Applicable Versions	Bundle Contents	
		Robot	00000
	LD 60 / LD 90 / LD 250	Robot, Dock	00002
Standard	10 250	Robot, Dock, Joystick, Top Plate	10004
Standard		Robot	00010
	Cart Transporter	Robot, Dock	00012
		Robot, Dock, Joystick, Top Plate, Acuity, Cart	01014
		Robot	20000
ESD	LD 60 / LD 90 / LD 250	Robot Dock	20002
		Robot, Dock, Joystick, Top Plate	20004

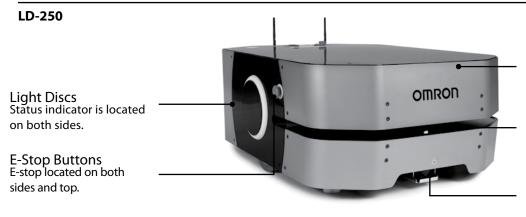


### LD Series

# **Components and Functions**



# **Components and Functions**



Hardened Construction Metal chassis and skins for increased duty and durability.

Safety Scanning Laser Safety-rated laser used for SLAM (Simultaneous Localization and Mapping) and safety functionality.

Low Front Laser Obstacle sensor detects low-profile objects when moving forward.

**Operation Panel** Access to system power, E-Stop, and the operation status display.

Charge Dock Integrated contacts for automated charging.

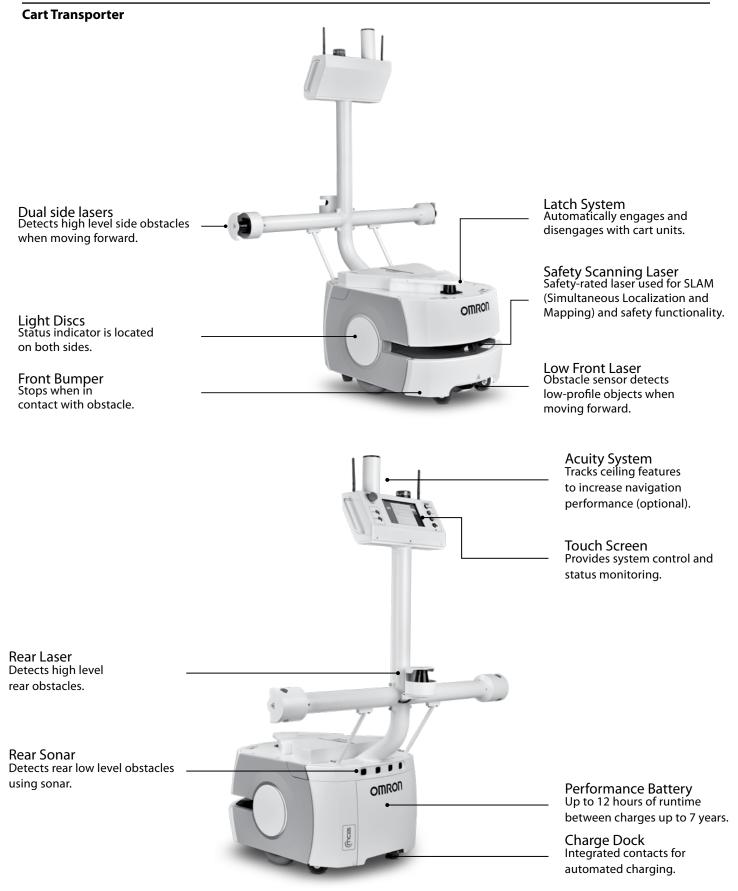
Aux Power & I/O Internal connections to power and control custom topper modules.

Performance Battery Up to 13 hours of runtime between charges for up to 7 years.

**Rear ToF Sensors** Detects rear obstacles using infrared light.



# **Components and Functions**



# LD Series Options and Accessories

Appearance	Description	Specification	Configuration & Attachment	Part Number
	A combined in Card	Single sensor - LD-60/ LD-90	Sensor $\times$ 1, mounting bracket $\times$ 1, power connector $\times$ 1, RS-232 connector $\times$ 1, 25 mm wide magnetic tape (south top side, 50 m roll)	13660-100
High Accuracy	A combination of sensor and magnetic tape to achieve accurate alignment during	Double sensor - LD-60/ LD-90	Sensor $\times$ 2, mounting bracket $\times$ 2, power connector $\times$ 1, RS-232 connector $\times$ 2, 25 mm wide magnetic tape (south top side, 50 m roll)	13660-000
Positioning System (HAPS)	forward driving motion, when the sensor is attached to mobile robot and magnetic tape is on	Single sensor - LD-250	Sensor $\times$ 1, mounting bracket $\times$ 1, power connector $\times$ 1, RS-232 connector $\times$ 1, 25 mm wide magnetic tape (south top side, 50 m roll)	21374-100
	the floor.	Double sensor - LD-250	Sensor $\times$ 2, mounting bracket $\times$ 2, power connector $\times$ 1, RS-232 connector $\times$ 2, 25 mm wide magnetic tape (south top side, 50 m roll)	21374-000
Magnetic tape	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the mobile robot where to stop	25 mm wide magnetic tape (south top side, 50 m roll)		14925-000
Cell Alignment Positioning System (CAPS)	Add on software license that improves the AMR's positional accuracy	Software license	License activation for CAPS (Activated on AMR)	20271-805
0	Upwards facing camera that maps ceiling features/lights used where process layout or		Camera, mounting kit, cables, leveling kit	13700-000
Acuity Localization	obstacle location changes often. Installed on a payload structure attached to the mobile robot.		Camera, mounting kit, cables	13700-100
Touchscreen	Allows operators to check the status of the mobile robot, enter goals, and pause the mobile robot. Installed on a payload structure attached to the mobile robot.	-	Touchscreen with bracket, power supply with bracket, power cable from core to power supply (33 cm), power cable from power supply to touchscreen (183 cm), Ethernet cable between touchscreen and core (153 cm), gasket between touchscreen and AMR mounting surface, software package including touchscreen support	13605-000
	Used to detect obstacles that are at heights the safety scanning laser of the mobile robot cannot	Bundle	Laser × 2, cable × 1	13456-000
Side Laser	detect. Installed on a payload structure attached to the mobile robot.	Kit	Laser $\times$ 2, Cable $\times$ 1, mounting kit $\times$ 2, metal cover $\times$ 2	13456-100
	Used to issue a request for a	WiFi	Call/door box	13029-802
Call/Door Box	mobile robot to go to the goal or to open a closed door. Installed at the goal or door	Wired	Call/door box	13029-902
Battery	A battery that is installed in the mobile robot	72 Ah Battery cell nominal capacity	Battery for all LD Series AMRs	20452000
AMR Legacy Upgrade Dongle	USB license dongle for AMRs migrating from MMS 4.x to FLOW Core	-FLOW Core	USB dongle with FLOW Core license (Only for AMRs migrating from MSS 4.x to FLOW Core)	13131-100F

# LD Series

Appearance	Description	Specification	Configuration & Attachment	Part Number
0		-	Docking station, AC power cable	12477-000
Docking Station	A docking station to charge the battery installed in the mobile robot.	Extended Wall mount	Docking station, AC power cable, extended wall mount (for Cart Transporter)	12477-050
Joystick	Used for manually controlling the mobile robot	Cable length: 0.6 to 3 m	-	13558-000
Breakout Cable	A D-SUB44 pin cable for digital I/O interface of the mobile robot.	-	DB44HD breakout cable (D-SUB44 pin cable for digital I/O interface)	14165-000
Top Plate - LD-60, LD-90	A upper plate of the mobile robot OEM. It is not necessary for building customer payload	Top cover for OEM type	LD-60 LD-90	12944-000
Top Plate - LD-250	A upper plate of the mobile robot OEM. It is not necessary for building customer payload	Top cover for OEM type	LD-250	20458-002
Cart*	A cart designed to work seamlessly with the mobile robot cart transporter.	-	The cart only applies to LD-CT models.	75020-000
Battery charging cable	A cable to connect a battery and docking station to charge the battery outside of the mobile robot	Cable length: 0.45 m	_	12676-000L

#### **Fleet Management Solutions**

Appearance	Product Name	Specification	Configuration & Attachment	Part Number
	Primary Fleet Manager		EM2100 Appliance with 120 day temporary Fleet Operations Workspace License	20271-900
	Secondary Fleet Manager		EM2100 Appliance with 120 day temporary Fleet Operations Workspace License	20271-901
	Fleet Simulator	Simulation of up to 10 AMRs	EM2100 Appliance with Simulation license included	20271-903
	5 Year License (Primary Fleet Management)		5 year license activation for primary fleet management	20271-806
	5 Year License (Secondary Fleet Management)		5 year license activation for secondary fleet management	20271-807
	Fleet Simulator License	Simulation of up to 10 AMRs	License activation for Fleet Simulation (Add-on License for Primary or Secondary Fleet Managers)	20271-804
strenge Van Strenge Van Transaction	MobilePlanner	Version 4.x	Installer (USB)* License Dongle MSS 4.x compatible only (NOT COMPATIBLE with FLOW Core)	13495-200

\* To obtain the latest version of the Fleet Operations Workspace (FLOW) Core software, contact your local OMRON representative.

# Specifications

# Mobile Robots-LD Platform LD-60, LD-90, LD-250, and Cart Transporter

literes	LD-60	, LD-90	LD-250	Cart Tra	Insporter	Nata
ltem	37032-	37042-	37222000	37142-	37162-	Note
Materials	Polycarbonate		Aluminum	Polycarbonate		
Dimension (L $\times$ W $\times$ H)	699 × 500 × 383 i	mm <sup>*1</sup>	963 × 718 × 383 mm *1	894 × 1074 × 13	94 mm *2	*1 Height to top plate *2 Height includes WiFi antenna
Weight (with Battery)	62 kg		148kg (with battery) 129kg (without battery)	81 kg (Vehicle)/23 kg (Cart)		
Environment						
Ambient temperature	5 to 40 °C					
Ambient humidity	5 to 95 % (non-co	ondensing)				
Operating Environment	Indoor usage onl	y, no excessive dus	t, no corrosive gas			Direct sunlight may cause safety laser false positive
IP rating	IP20					
Cleanroom rating	Fed Class 100, ISC	O Class 5				
Floor Conditions	•	-		<b>I</b>		
Floor Requirements	Linoleum, epoxy,	, or concrete (no wa	iter, no oil, no dirt)			
Minimum floor flatness	FF25 (ACI 117 sta	ndard)* <sup>3</sup>				*3 ACI 117 is the American Concrete Institute standard for concrete floors. FF is flatness, FL is the level. Higher FF numbers represent flatter floors. FF25 is a fairly lenient specification.
Traversable step	15 mm max*4	10 mm max*4	10 mm max *5	5 mm max. *6	5 mm max. *6	*4 A speed of 250-300 mm/s and 250
Traversable gap	15 mm max	15 mm max	15 mm max	5 mm max. *6	5 mm max. *6	mm/s, for the LD-60 and LD-90, is required for these steps. Faster or frequent driving over such steps or gaps will shorten the lifespan of the drivetrain components. Lower speeds may not traverse the step. Steps should have smooth, rounded profiles. *5 For LD-250, the robot should traverse the 10mm step at 600 mm/s or slower for best performance of the laser and battery *6 The Cart Transporter with a cart is capable of driving over a gap or step of 5 mm at a speed of 250 mm/s, but this should not be regarded as normal use. Regular driving over such gaps or steps will shorten the lifespan of the drivetrain components.
Climb grade	Below 1: 12 (60 k Flat floor only (ov		Flat floor only (full payload)	Flat floor only		
Navigation			1			
Routing	Autonomous rou	iting by localizing w	/ith safety scanning laser based on e	nvironment mapping	3	
Environmental map making method	Scan by walking	the mobile robot th	rough the environment, and upload	l the scan data in the	MobilePlanner	
Payload						
Maximum Weight	60 kg	90 kg	250 kg	105 kg*7	130 kg*7	*7 Excluding cart weight
Mobility						
Maximum Speed	1800 mm/s	1350 mm/s	1200mm/s	1350 mm/s	900 mm/s	
Maximum Rotation Speed	180°/s	180°/s	120°/s	100°/s		
Stop Position Accuracy (Single AMR)	± 65 mm position Standard target With CAPS ±8m With HAPS ±8m	±25mm / ±2° 1m / ±0.5°	± 75 mm position Standard target ±25mm / ±2° With CAPS ±8mm / ±0.5° With HAPS ±8mm / ±0.4°	± 65 mm positic Standard targe With CAPS ±8r With HAPS ±8r	t ±25mm / ±2° nm / ±0.5°	
Stop Position Accuracy (Fleet)	± 85 mm position Standard target With CAPS ±12 With HAPS ±10	±35mm / ±2° mm / ±0.5°	$\pm 100mm$ position Standard target $\pm 35mm$ / $\pm 2^{\circ}$ With CAPS $\pm 14mm$ / $\pm 0.6^{\circ}$ With HAPS $\pm 10mm$ / $\pm 0.6^{\circ}$	± 85 mm positic Standard targe With CAPS ±1 With HAPS ±10	t ±35mm / ±2° 2mm / ±0.5°	

		1.5.000		
ltem	LD-60, LD-90	LD-250	Cart Transporter	Note
	37032 37042	37222000	37142-	
Drive wheel		1	Numeral in a star from filled	1
Materials	Non-marking nylon foam-filled rubber, non-conductive	Aluminum with polyurethane tread	Non-marking nylon foam-filled rubber, non-conductive	
Size	200 dia. $\times$ 50 mm nominal, 2 wheels			
Passive caster		1		1
Materials	Conductive thermoplastic rubber on polyolefin	Conductive solid polyurethane	Conductive thermoplastic rubber on polyolefin	
Size	75 dia. × 41 mm nominal, 4 casters	127 dia. × 51 mm nominal, 4 casters	75 dia. × 41 mm nominal, 4 casters	
Power		·	·	·
Battery	22-30 VDC			
Capacity	72 Ah Battery cell nominal capacity			
Run Time	15 hours (continuous) approx.	13 hours (continuous) approx	15 hours (continuous) approx.	With no payload condition
Recharge Time	4 hours (5:1 ratio) approx.			
Battery Life Cycles	2,000 recharge cycles (battery cell n	ominal)		
Charging Method	Automatic / manual			
Auxiliary Power	5 VDC±5%, 1 A switched Aux power 12 VDC±5%, 1 A switched Aux power 20 VDC±5%, 1 A switched Aux power 22-30 VDC, 4 A switched × 2 22-30 VDC, 10 A switched* <sup>10</sup> 22-30 VDC, 10 A safe, switched* <sup>10</sup>	er		5, 12, 20, and 22-30 VDC power can be provided to external devices *10. 10 A switched and 10 A safe, switched share the 10 A of current
Standard				
Harmonized Standard	EN IS0 12100 / EN ISO 13849-1 / EN 6	50204-1		
Relevant Standard	EN 1525 / ANSI B56.5			
Wireless	IEEE 802.11 a/b/g			
Safety Features				
Safety Scanning Laser	1 at front Class 1 PLd safety per ISO13849-1 3 m maximum radius from laser for : 40 m radius for general sensing 240° field of view	safety zones		
Emergency Stop	1 at operator panel	1 at operator panel, 1 on each side (3 total)	1 at HMI post touchscreen, 1 at operator panel	
Rear Sonar	2 at rear, 2 m range	Time of flight (TOF) sensors	2 at rear, 2 m range	Each pair includes one emitter and one receiver working together
Front Bumper	1 at front of platform, 2 pairs of sensors	Fixed, non-sensing	1 at front of platform, 2 pairs of sensors	
Low Front Laser	1 at front of platform Class 1 4 m maximum range 126° field of view			
Side Laser	Option*11		2 on horizontal tubes of HMI post Class 1 4 m maximum range 270° field of view	*11. 2 on sides of payload structure, usermounted
Indicators	Light disc on each side		Light disc in each side, beacon on HMI post	
Speaker	3.5 in., 80 W max.			
Operator Interface				
Screen / Touch Panel	3.5 in. TFT 320 $\times$ 240 pixels, color scr	een	7.0 in. TFT LCD touch panel, 18/24 bit RGB	
Button	On button: green Off button: red Brake-release button: orange Keyswitch (disabled off button) *12		On button: green Off button: red Brake-release button: orange Keyswitch (disabled off button) *12, Latch button, unlatch button	*12. Key switch can be used to disable the off button to avoid accidental shutdown or tampering.
User Interface				
Wireless	IEEE 802.11 a/b/g			
Ethernet Port	1 x user LAN, 1 x maintenance LAN, Auto-MDIX			
Serial	RS-232 × 2			
Digital I/O	16 inputs, 16 outputs			
Analog I/O	8 inputs (0 to 30 V), 4 outputs (0-20 V)			
Audio	Digital audio out, audio in / audio out			
Cart Latching				
Latching Method	Not available		Automatic	
	L		1	1

#### MobilePlanner Software

Operating System	Windows 10 (32-bit/64-bit version)
CPU	1.5 GHz dual-core CPU recommended
Main Memory	1.5 GB min. (4 GB min. recommended)
Hard Disk	At least 200 MB of available space
Video Memory	256 MB min.
Display	XGA 1024 × 768, 16 million colors
Supported Languages	Japanese, English, German

# Fleet Manager

Dimensions - W × D × H	430 × 495.3 × 43.7 mm
Weight	9.1 kg
Mounting method	1U rack mount in a standard 19-inch equipment rack
Power Supply	100-240 VAC (typical 100 W)
Power Consumption	200W max.
Operating Temperature	10 to 35 °C
Storage Temperature	-25 to 60 °C
Operating Humidity	8 to 90%, non-condensing
Storage Humidity	5 to 95%, non-condensing
Chassis protection class	IP20
CPU	Intel® Xeon® CPU
Main Memory	32 GB DDR3
Storage	60 GB SSD
Archive Storage	4 TB HDD
Communication port	10/100/1000 Ethernet × 4, USB × 4, VGA
Status Display	Multi-segment LCD

#### **High Accuracy Positioning System**

Part Number		1366000 (LD-60/90/105CT/130CT) 2137400 (LD-250)	
	Depth	30 mm	
	Width	160 mm	
Sensor	Rating	IP64	
Sensor	Environment	-40 to 85 °C	
	LEDs	Power, tape present, left marker, right marker	
Magnetic Tape	Width	25 mm	
Magnetic Tape	Orientation	South up	
	Length	25 mm	
Markers (Magnetic Tape)	Orientation	300 mm min. for 500 mm/s drive speed North up	
(magnetic tape)	Separation From Tape	15 - 30 mm	
	Front Sensor	RS232-1 (/dev/ttyUSB9) on the core	
Connections	Rear Sensor	RS232-2 (/dev/ttyUSB10) on the core	
	Power, Both Sensors	Aux power using the included splitter cable	

#### **Acuity Localization**

Part Number	1370000
Field of View	140°
Power Input	12 VDC (±10%) supplied from platform through power connector
Power Consumption	3.3 W maximum

# Cell Alignment Positioning System (CAPS)

Stop Position Accuracy	* ±25 mm position, ±1.0° rotation	
Туре	Software license	

#### Touchscreen

Part Number	13605-000
Touch Panel	PCAP touch sensor, black-bordered cover lens
TFT Display	TFT LCD panel, 18/24 bit RGB parallel interface, 7.0 in. WVGA - wide viewing angles, 5-touch
Backlight	Constant current LED supply
Power Input	5 VDC supplied through power connector
Power Consumption	6.5 W maximum

#### **Call/Door Box**

Part Number	WiFi	13029-802
	Wired	13029-902
Dimensions- $W \times D \times H$	141.4 × 74.7 × 30 mm	
Weight	190 g	
Mounting method	Mount to the provided wall frame with four screws	
Power Supply	12 VDC	
Power Consumption	0.5 A, 6 W typical	
WiFi	IEEE 802.11 a/b/g/n	
Communication Port	Ethernet	
I/O	Input × 2, output × 2 (30 VDC, 2 A max.)	

#### Battery

Run Time (No Payload)	15 hours (continuous) approx. (LD-60/90) 13 hours (continuous) approx. (LD-250)	
Weight	19 kg	
Voltage	22-30 VDC	
Capacity	72 Ah (battery cell nominal)	
Recharge Time	4 hours approx.	
Life Expectancy	2,000 times 80% DOD (battery cell nominal), 7 years, approx., 16 hrs/day, 5 days/wk 4 years, approx., 19/7 (full-time)	

#### **Docking Station**

Part Number	12477-000, 12477-050	
Current	8 A*1	
Contacts	2	
Power	100 to 240 VAC, 50 to 60 Hz	
Power Consumption	800 W	
Humidity	5 to 95 %, non-condensing	
Temperature	5 to 40° C	
Dimensions (W $\times$ D $\times$ H)	349 × 369 × 315 mm 495 × 495.5 × 317 mm (with floor plate)	
Weight	8.2 kg	
Mounting	Wall bracket, directly to floor, or on floor with floor plate	
Indicators	Power on: blue Charging: yellow	
Connector	For out-of-platform battery charging	

\*1 Thermal fuse in AC power switch (10 A time-lag fuse at switch for legacy

#### Joystick

Part Number	13558-000
Weight	0.55 kg
IP Rating	IP56

#### Cart

Part Number	75020-000	
Dimensions (L $\times$ W $\times$ H)	592 × 846 × 480 mm	
Weight	23 kg	
Rating	ESD-rated	
Passive Casters	2 front, 2 rear, spring-loaded	
Caster Diameter	100 mm nominal	
Caster Brakes	At 2 rear casters	

# Dimensions

LD-250

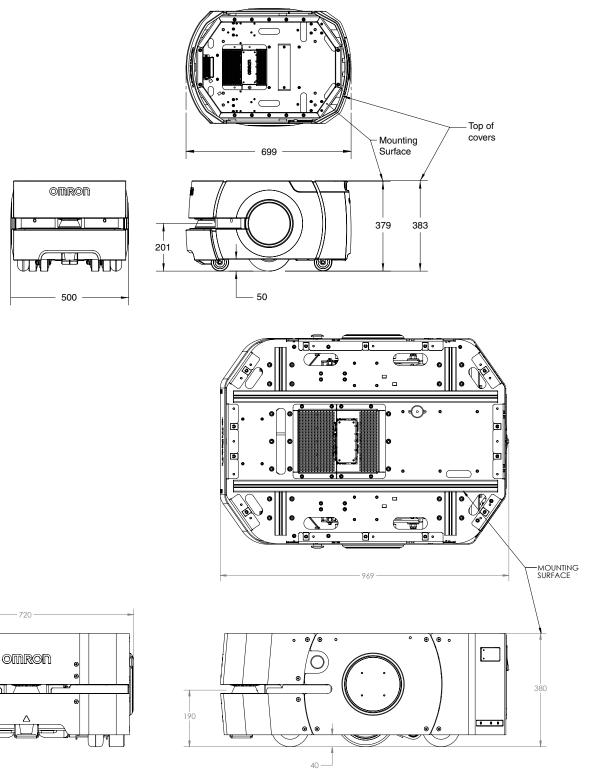
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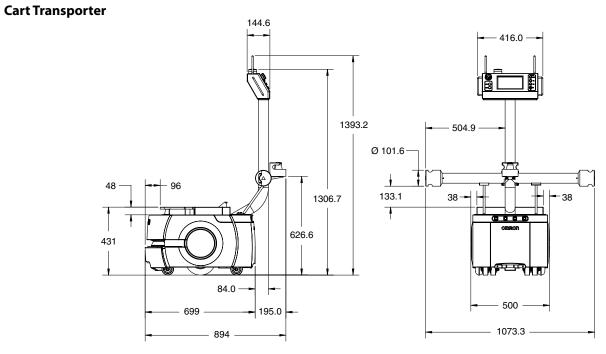
CAD data can be downloaded from Omron's website. https://automation.omron.com/en/us/support/cad-library

(Unit: mm)v

Mobile Robots-LD Platform LD-60, LD-90

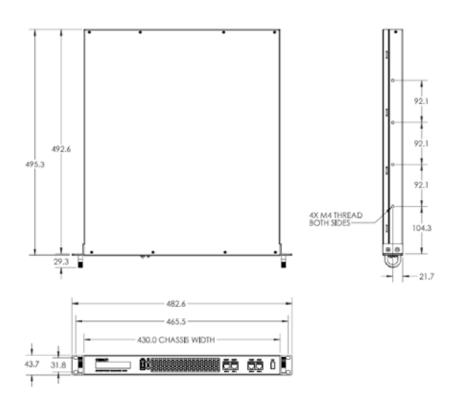


# **Dimensions**



# Fleet Manager EM2100 Appliance

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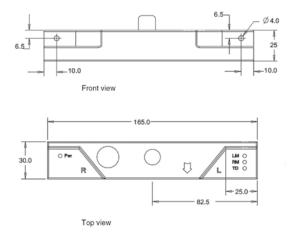


# **LD Series**

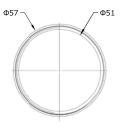
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# **Dimensions**

# **High Accuracy Positioning System**

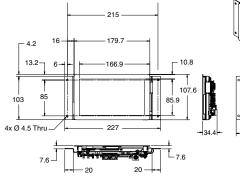


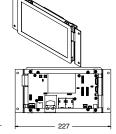
#### **Acuity Localization**

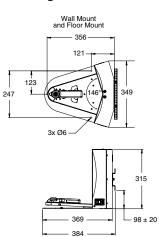


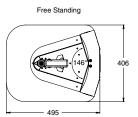


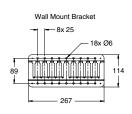
# Touchscreen



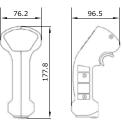




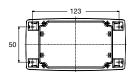




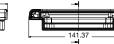
Joystick

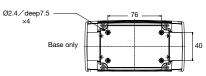


### Call/Door Box

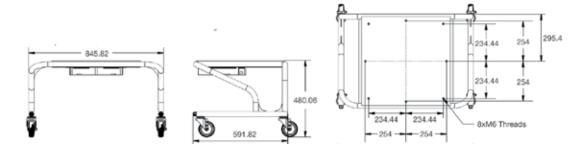








Cart



# **Docking Station**

# **Related Manuals**

Manual No.	English Title	
l611	Mobile Robots LD Platform User Guide	
l612	Mobile Robots LD Cart Transporter User Guide	
l613	Mobile Robots LD Platform Peripherals Guide	
l614	Mobile Robots Software Suite User Guide	
l615	Enterprise Manager User Guide	
l616	Mobile Robot LD Safety Guide	
l617	Advanced Robotics Command Language Reference Guide	
l618	Advanced Robotics Command Language Enterprise Manager Integration Guide	
1634	EM2100 Installation Guide	
1635	Fleet Operations Workspace Core User Guide	
1636	Fleet Operations Workspace Core Migration Guide	
1637	Fleet Operatiom Workspace Core Integration Toolkit User Guide	
1642	LD-250 Platform User Guide	

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Note: Specifications are subject to change.